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Fundamentals of Systems Engineering

Prof. Olivier L. de Weck
20 November 2015

Session 10

Commissioning and Operations

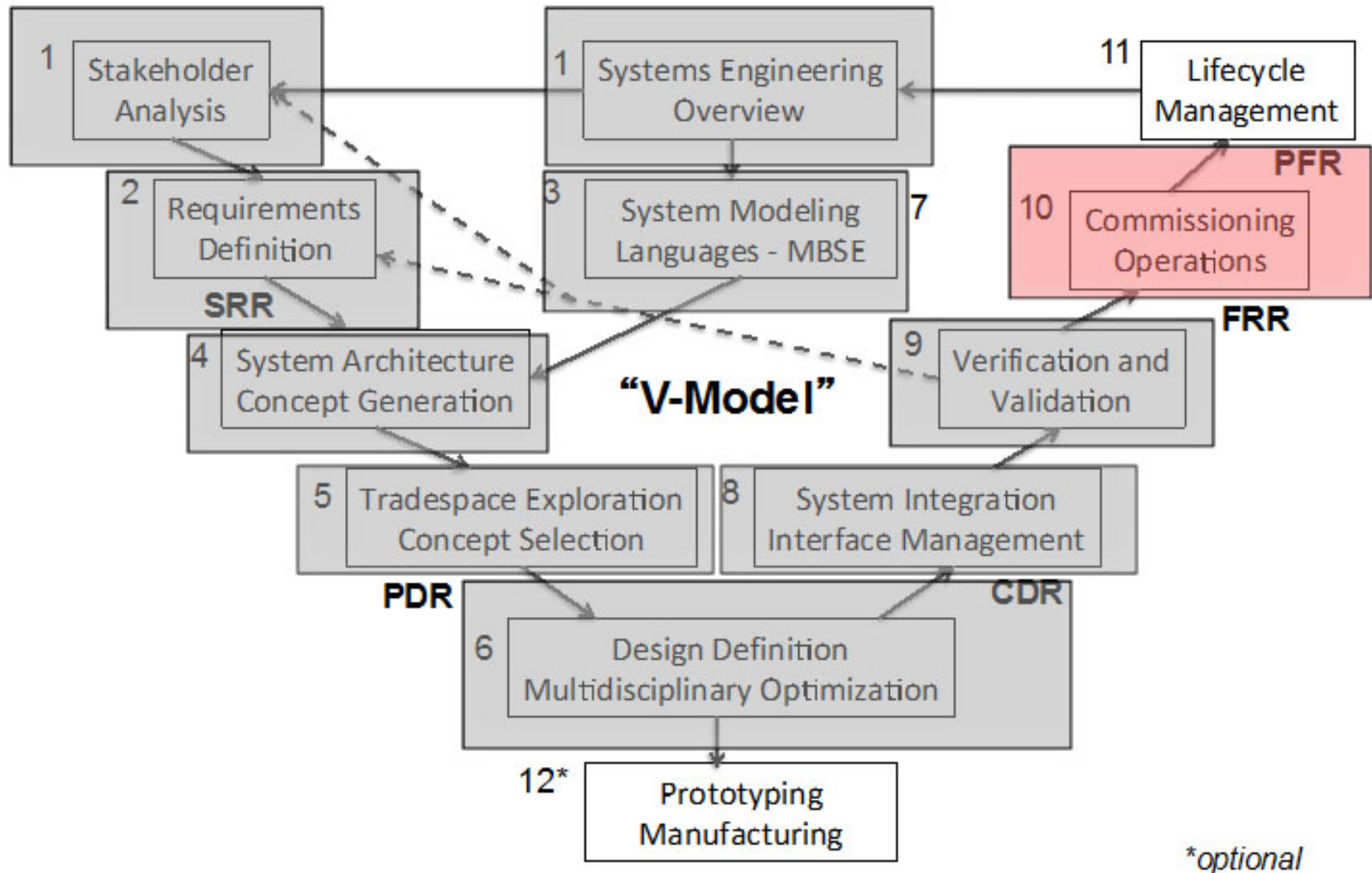
General Status Update

<i>Assignment</i>	<i>Topic</i>	<i>Weight</i>
A1 (group)	Team Formation, Definitions, Stakeholders, Concept of Operations (CONOPS)	12.5%
A2 (group)	Requirements Definition and Analysis Margins Allocation	12.5%
A3 (group)	System Architecture, Concept Generation	12.5%
A4 (group)	Tradespace Exploration, Concept Selection	12.5%
A5 (group)	Preliminary Design Review (PDR) Package and Presentation	20%
Quiz (individual)	Written online quiz	10%
Oral Exam (individual)	20' Oral Exam with Instructor 2-page reflective memorandum	10%

A5 is due today!

The "V-Model" of Systems Engineering

16.842/ENG-421 Fundamentals of Systems Engineering



Numbers indicate the session # in this class

**optional*

Outline for Today

- Operational Considerations
- Commissioning
- Research into Operations
 - Reconfigurability and Common Sparing for Mars Missions
 - Designing Systems for Operations in Partially Failed States
- Post-Flight Review (PFR)

The question ...

- Why would a small mountainous country select a U.S. Navy military aircraft originally designed for a completely different operational mission?

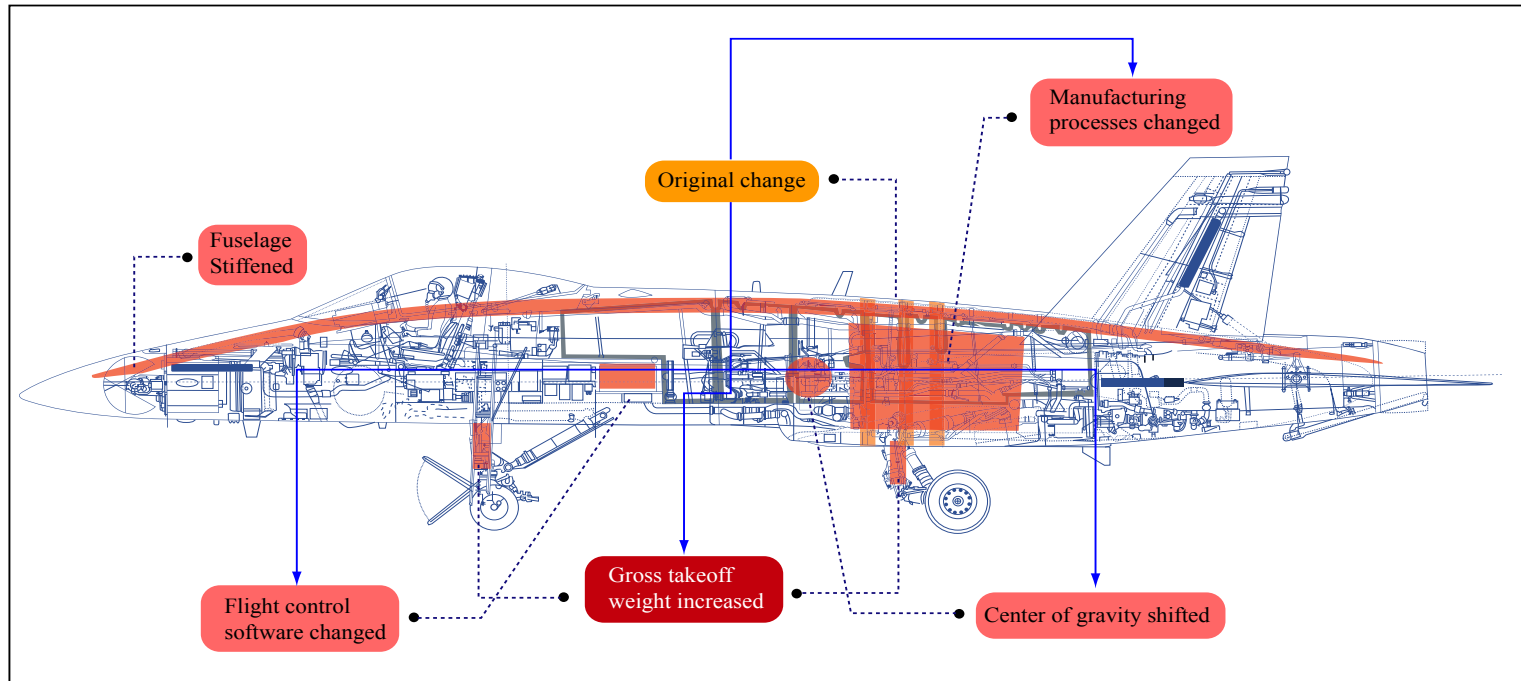


Image by MIT OpenCourseWare.

■ Answer: Superior Lifecycle Properties

- A) Flexibility (air patrol, intercept, ground attack)
- B) Maintainability (21 vs 56 DMMH/FH)
- C) Evolvability (spare capacity, e.g. in LEX)

Flight Operations



Turn-to-Partner Exercise

- What has been **your experience with operations** of a cyber-physical system? Did the system start-up well? What were the challenges? What would you do differently if you could do it again?
- Discuss.
- Share.

F/A-18 Fatigue Life Monitoring

International Journal of Fatigue

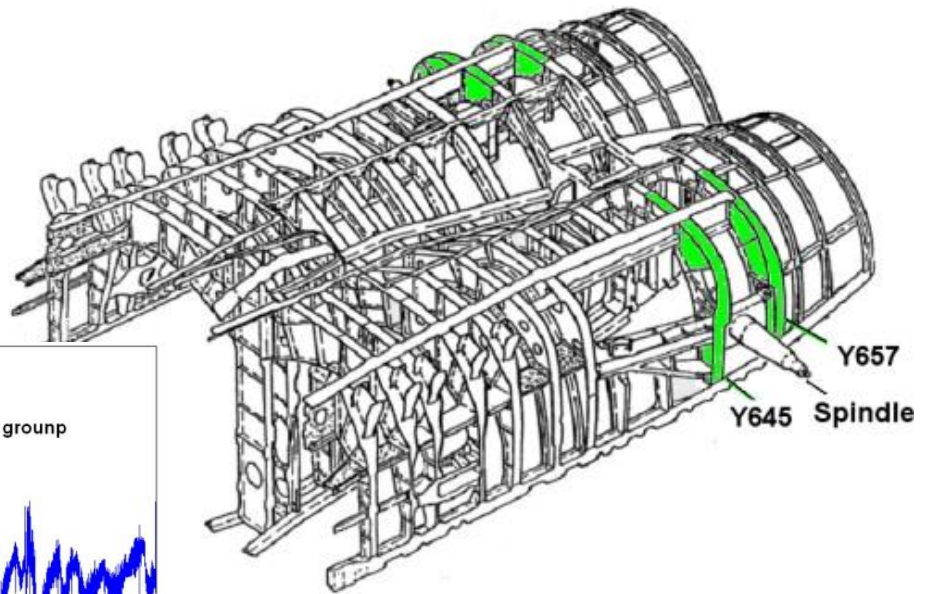
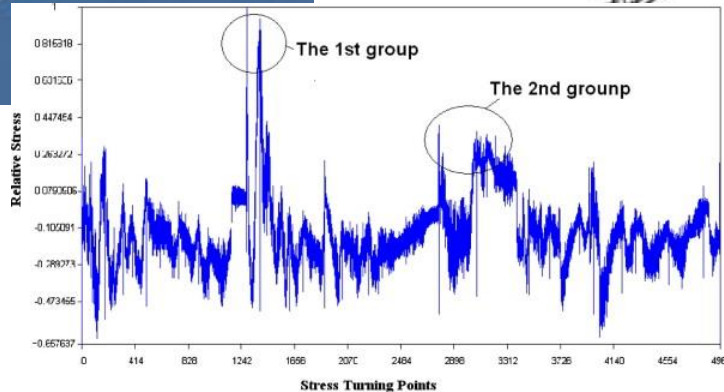
Volume 29, Issues 9–11, September–November 2007, Pages 1647–1657

Fatigue Damage of Structural Materials VI

The Sixth International Conference on Fatigue Damage of Structural Materials

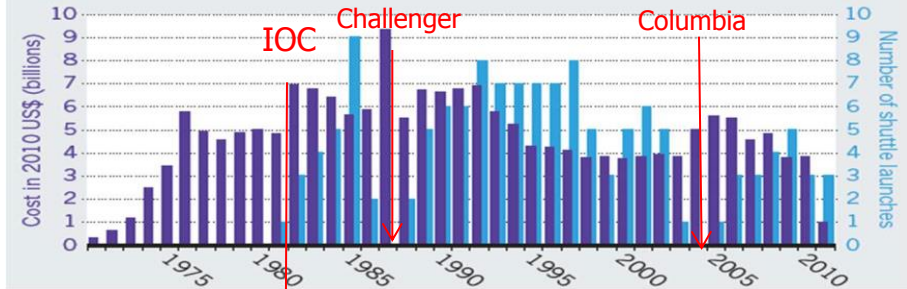
Flight-by-flight fatigue crack growth life assessment

W. Zhuang, , S. Barter, L. Molent

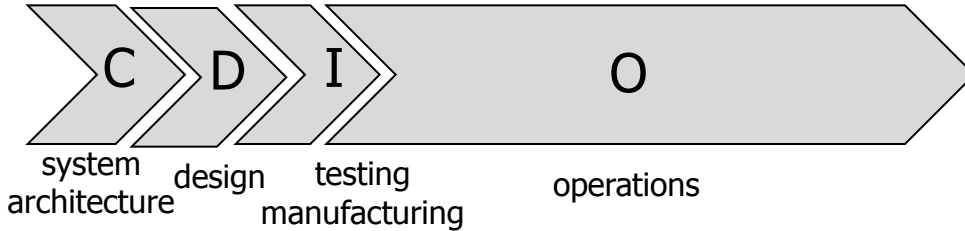


Space Shuttle Lifetime Cost (1971-2011)

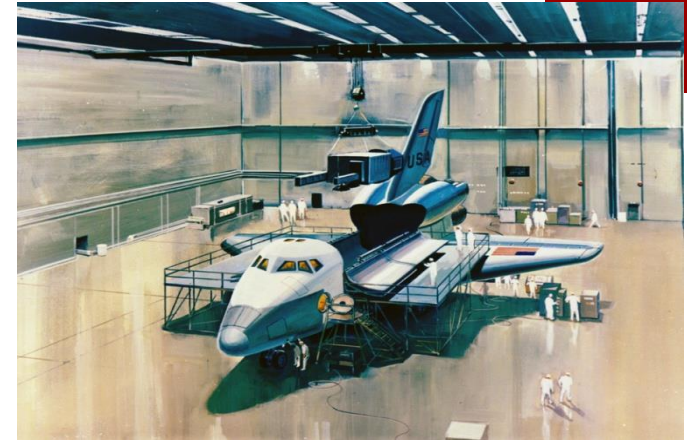
A COSTLY ENTERPRISE \$192B Total, 135 launches
 The average cost per launch was about \$1.5 billion over the life of the US space-shuttle programme.



Roger Pielke Jr & Radford Byerly, Shuttle programme lifetime cost, *Nature* 472, 38 (07 April 2011)



What we wanted



This image is in the public domain.

What we got



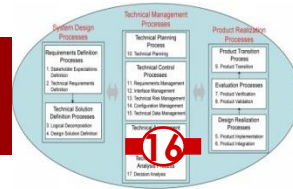
This image is in the public domain.

- Vision: partially reusable space vehicle with quick turnaround and high flight rate
- Actual: complex and fragile vehicle with average cost of about \$1.5B/flight (20,000 workforce)
- **Why?**
 - Overoptimism
 - Congress capped RDT&E at \$B5.15 (1971)
 - Focus on achieving launch performance (24 mt LEO)
 - Maintainability needed to be “designed-in”
 - No realistic lifecycle cost/value optimization done

Operational Considerations

- How will the system be operated?
- What insights do the operators need into the system status?
- Before turning over to the operators what checks need to be performed?
- How might the system fail?
- What options are available to the operators in the event of system failures?!
 - What spares are needed to repair the system?
 - Will the system still perform even under partial failures?

NASA Life-Cycle Phases



NASA Life Cycle Phases	FORMULATION			IMPLEMENTATION			
	<i>Pre-Systems</i>	<i>Acquisition</i>	<i>Approval for Implementation</i>	<i>Systems Acquisition</i>	<i>Operations</i>	<i>Decommissioning</i>	
Project Life Cycle Phases	Pre-Phase A: Concept Studies	Phase A: Concept & Technology Development	Phase B: Preliminary Design & Technology Completion	Phase C: Final Design & Fabrication	Phase D: System Assembly, Int & Test, Launch	Phase E: Operations & Sustainment	Phase F: Closeout
Project Life Cycle Gates & Major Events	KDP A FAD Draft Project Requirements	KDP B Preliminary Project Plan	KDP C Baseline Project Plan ⁷	KDP D	KDP E Launch	KDP F End of Mission	Final Archival of Data
Agency Reviews	ASP ⁵	ASM ⁵					
Human Space Flight Project Reviews¹	MCR	SRR SDR (PNAR)	PDR (NAR)	CDR / PRR ²	SIR SAR	ORR FRR PLAR CERR ³	DR
Re-flights					Inspections and Refurbishment		
Robotic Mission Project Reviews¹							
Launch Readiness Reviews	MCR	SRR MDR ⁴ (PNAR)	PDR (NAR)	CDR / PRR ²	SIR	ORR FRR PLAR CERR ³	DR
Supporting Reviews						SMSR, LRR (LV), FRR (LV)	
		Peer Reviews, Subsystem PDRs, Subsystem CDRs, and System Reviews					

FOOTNOTES

- Flexibility is allowed in the timing, number, and content of reviews as long as the equivalent information is provided at each KDP and the approach is fully documented in the Project Plan. These reviews are conducted by the project for the independent SRB. See Section 2.5 and Table 2-6.
- PRR needed for multiple (≥4) system copies. Timing is notional.
- CERRs are established at the discretion of Program Offices.
- For robotic missions, the SRR and the MDR may be combined.
- The ASP and ASM are Agency reviews, not life-cycle reviews.
- Includes recertification, as required.
- Project Plans are baselined at KDP C and are reviewed and updated as required, to ensure project content, cost, and budget remain consistent.

ACRONYMS

ASP—Acquisition Strategy Planning Meeting
 ASM—Acquisition Strategy Meeting
 CDR—Critical Design Review
 CERR—Critical Events Readiness Review
 DR—Decommissioning Review
 FAD—Formulation Authorization Document
 FRR—Flight Readiness Review
 KDP—Key Decision Point
 LRR—Launch Readiness Review
 MCR—Mission Concept Review
 MDR—Mission Definition Review
 NAR—Non-Advocate Review
 ORR—Operational Readiness Review
 PDR—Preliminary Design Review
 PPAR—Post-Flight Assessment Review
 PLAR—Post-Launch Assessment Review
 PNAR—Preliminary Non-Advocate Review
 PRR—Production Readiness Review
 SAR—System Acceptance Review
 SDR—System Definition Review
 SIR—System Integration Review
 SMSR—Safety and Mission Success Review
 SRR—System Requirements Review

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Transitioning and Operating

Phase D

System Assembly, Integration and Test, Launch

To assemble and integrate the products to create the system, meanwhile developing confidence that it will be able to meet the system requirements. Launch and prepare for operations. Perform system end product implementation, assembly, integration and test, **and transition to use.**

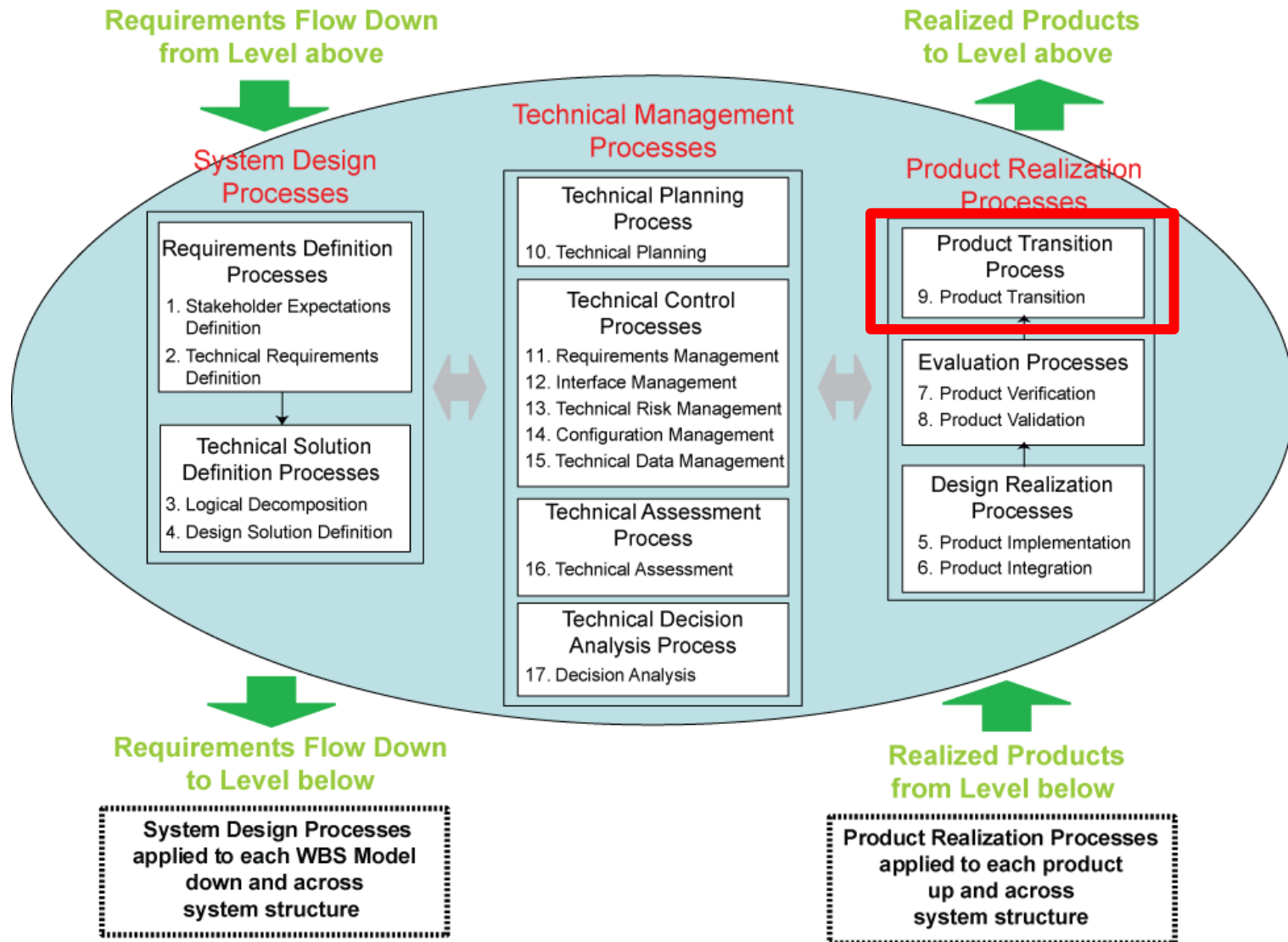
Phase E

Operations and Sustainment

To conduct the mission and meet the initially identified need and maintain support for that need. Implement the mission operations plan.

Common Technical Processes

“SE Engine”



NASA Product Transition Process

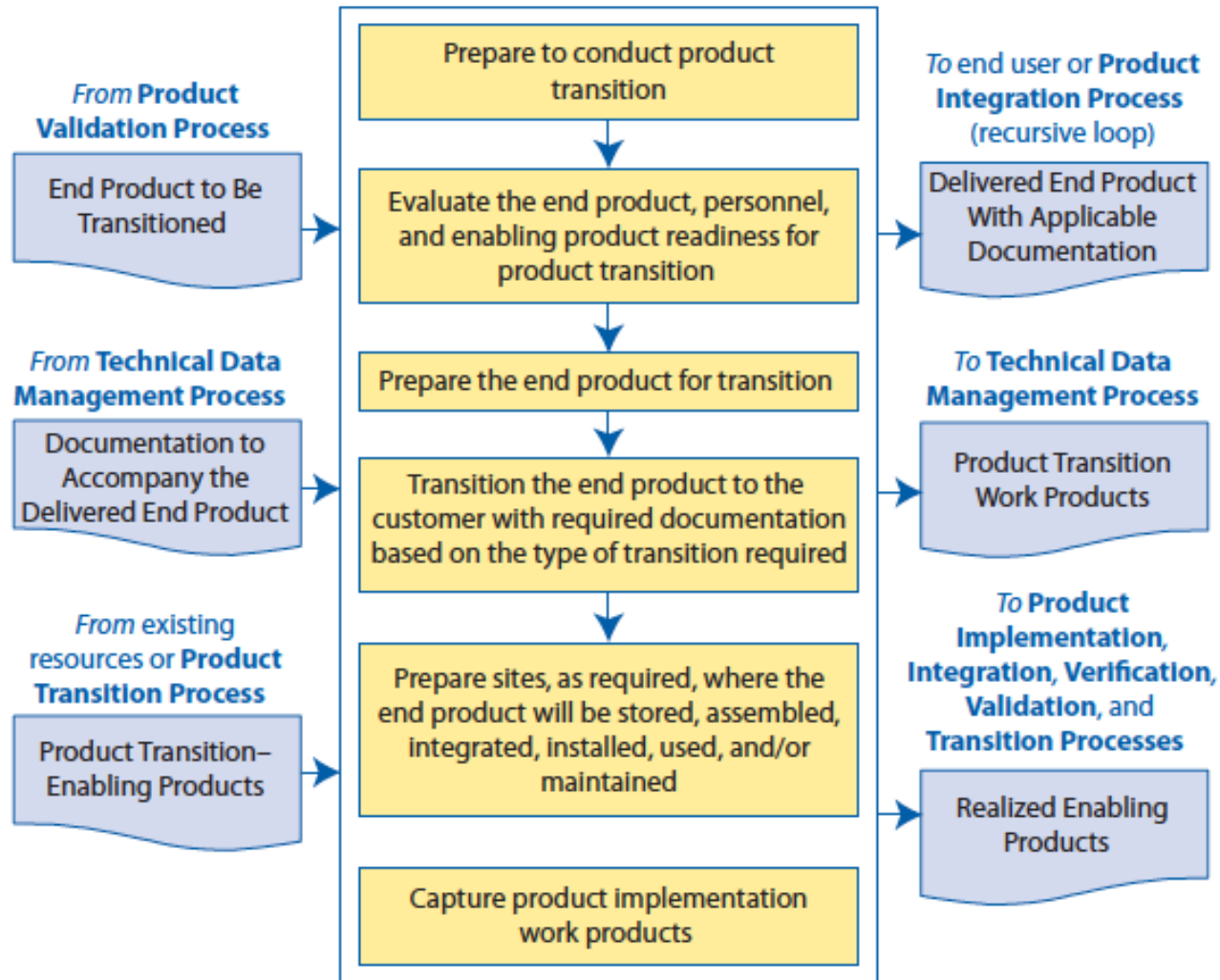


Figure 5.5-1 Product Transition Process

Pg. 106, NASA SE Handbook

Product Transitioning → Commissioning

- Deploying System in the Field
 - Transition to operators (legally and physically)
 - Training of operators
- Checkout
 - Turning on all systems and subsystems
 - Comparing predicted parameters against actual behaviors
- Sustainment
 - Maintenance (preventative, corrective)
 - Spare Parts Management
 - Reconfiguring Systems during Use, Upgrades
 - Retrofits

NASA Operations Phases

Table 4.1-1 Typical Operational Phases for a NASA Mission

Operational Phase	Description
Integration and test operations	<p>Project Integration and Test: During the latter period of project integration and test, the system is tested by performing operational simulations during functional and environmental testing. The simulations typically exercise the end-to-end command and data system to provide a complete verification of system functionality and performance against simulated project operational scenarios.</p> <p>Launch Integration: The launch integration phase may repeat integration and test operational and functional verification in the launch integrated configuration.</p>
Launch operations	<p>Launch: Launch operation occurs during the launch countdown, launch ascent, and orbit injection. Critical event telemetry is an important driver during this phase.</p> <p>Deployment: Following orbit injection, spacecraft deployment operations reconfigure the spacecraft to its orbital configuration. Typically, critical events covering solar array, antenna, and other deployments and orbit trim maneuvers occur during this phase.</p> <p>In-Orbit Checkout: In-orbit checkout is used to perform a verification that all systems are healthy. This is followed by on-orbit alignment, calibration, and parameterization of the flight systems to prepare for science operations.</p>
Science operations	The majority of the operational lifetime is used to perform science operations.
Safe-hold operations	As a result of on-board fault detection or by ground command, the spacecraft may transition to a safe-hold mode. This mode is designed to maintain the spacecraft in a power positive, thermally stable state until the fault is resolved and science operations can resume.
Anomaly resolution and maintenance operations	Anomaly resolution and maintenance operations occur throughout the mission. They may require resources beyond established operational resources.
Disposal operations	Disposal operations occur at the end of project life. These operations are used to either provide a controlled reentry of the spacecraft or a repositioning of the spacecraft to a disposal orbit. In the latter case, the dissipation of stored fuel and electrical energy is required.

JWST Deployment Video

JWST Deployment Video

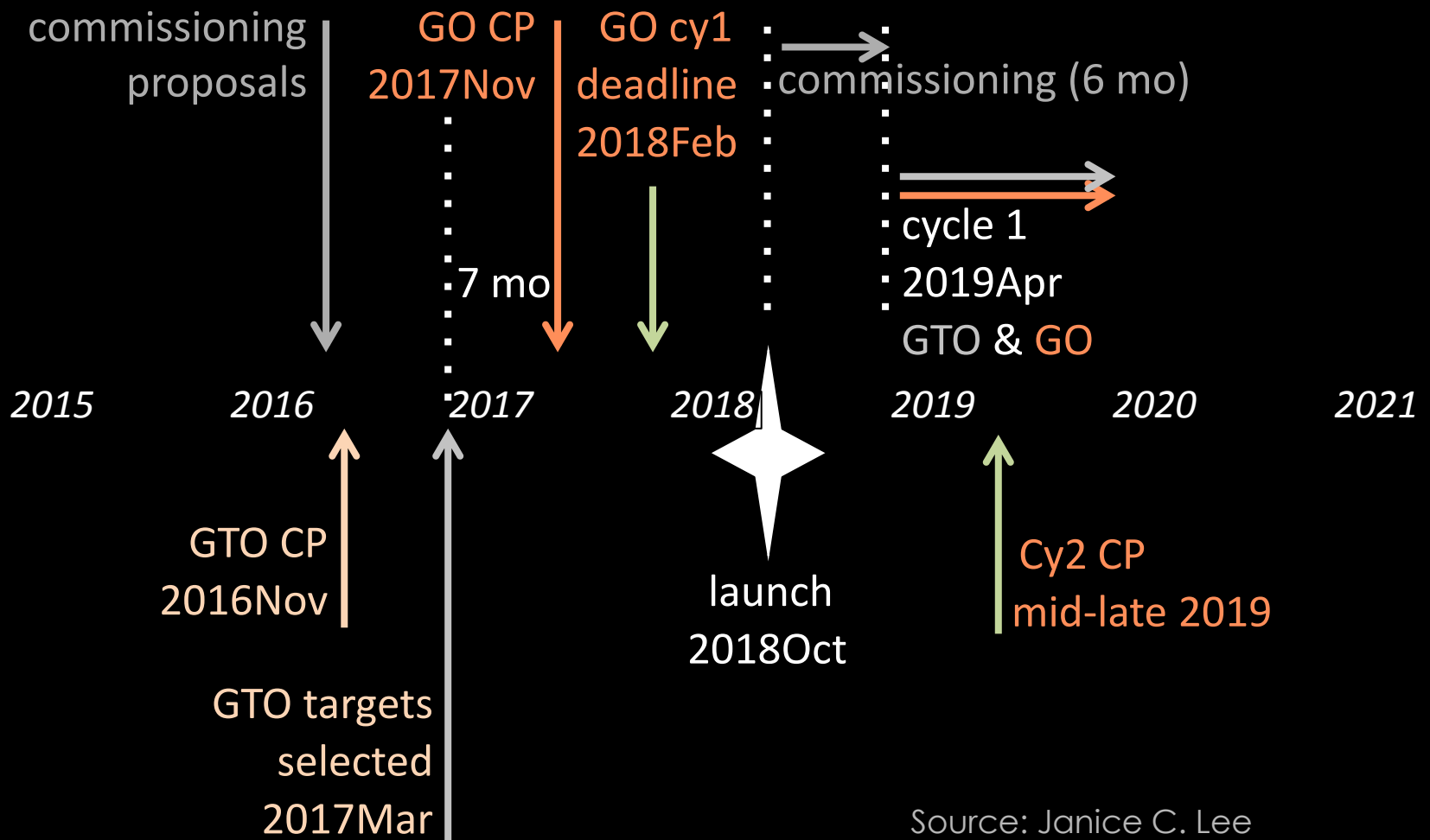
https://www.youtube.com/watch?v=N8h_6WgSMjs

Concept Question 10

- How long is the **commissioning phase** of the James Webb Space Telescope (JWST) before science operations can begin?
- 3 days
- 1 week
- 3 weeks
- 1 month
- 3 months
- 6 months
- Not sure

Answer Concept Question 10
(see supplemental files)

JWST Science Planning Timeline (as of 2014 Feb)



Source: Janice C. Lee
STScI Science Mission Office
March 13, 2014

JWST Timeline to Operations

Commissioning Program [6 mo: 2018 Oct-2019 Apr]

- *full schedule of deployment & check-out activities*
- *limited set of science calibration obs possible*
- *science obs highly unlikely*

Guest Observer Program [2019 Apr -]

- *use GO programs from HST, Spitzer, etc. as models*
- *will accommodate programs with range of sizes*
- *support archival research*
- *details TBD, consultations with JSTAC*

Guaranteed Time Observation Program [2019 Apr -]

- *3,960 hr total allocation in first 30 mo. after commissioning*
- *~10% of time available in nominal 5 yr lifetime*

Source: Janice C. Lee
STScI Science Mission Office
March 13, 2014

Outline for Today

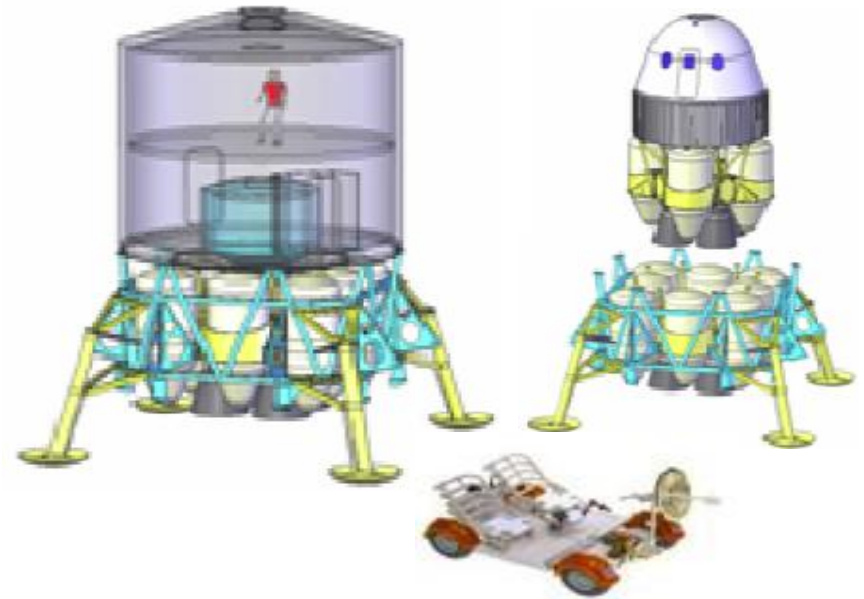
- Operational Considerations
- Commissioning
- **Research into Operations**
 - Reconfigurability and Common Sparing for Mars Missions
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Some research into operations

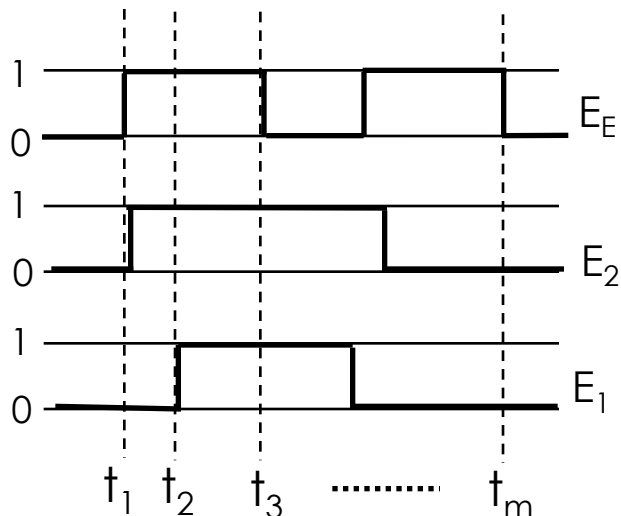
Siddiqi A., de Weck O., "Spare Parts Requirements for Space Missions with Reconfigurability and Commonality", *Journal of Spacecraft and Rockets*, 44 (1), 147-155, January-February 2007

Impact of Reconfigurability on Logistics

- Reconfigurability across different elements in a mission was explored
- Effect of reconfigurable spares on system availability was quantified through allowance of temporary scavenging/cannibalization



Element Operational Profiles



- Operational cycles of elements are defined
- The number of available spares become a function of time
- System availability as function of spares level will be used for quantifying impact

Spare Parts Requirements Model - I

Failures modeled as Poisson process

$$p(n) = \frac{e^{-\lambda} \lambda^n}{n!}$$

$$\lambda = \int_{t_o}^{t_f} l dt = ql\Delta t$$

$$\lambda_e(t_i) = q_e l \sum_{k=1}^i [t_k - t_{k-1}] \Gamma_e(t_k)$$

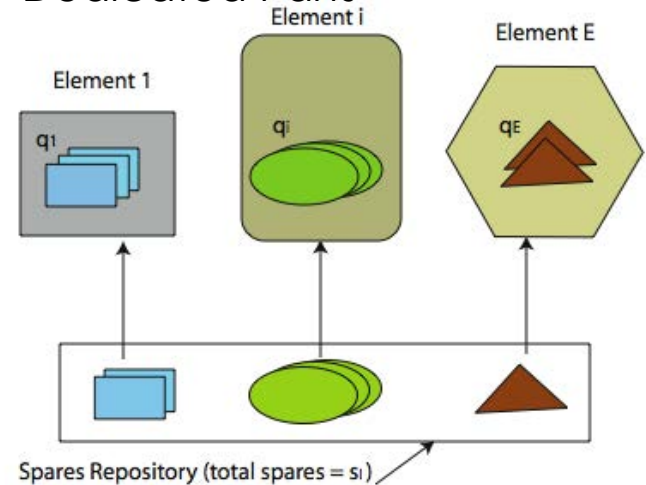
Spare parts from elements are function of time (operation profile)

$$s_E(t_i) = \sum_{e=1}^E q_e [-\Gamma_e(t_i)]$$

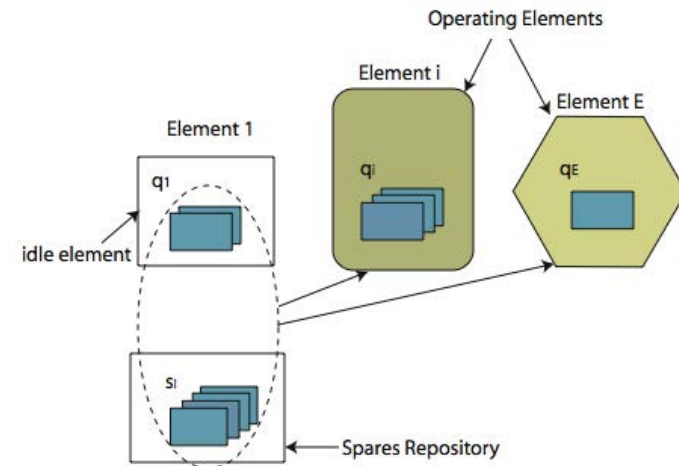
$$s(t_i) = s_I + s_E(t_i) - n_F$$

q : quantity per application (QPA)
 λ : mean failures
 n_f : # of failures
 $p(n)$: probability of n failures
 l : failure rate
 Γ : binary variable for operation
 s_E : spares from elements
 s_I : spares from repository
 s : total spares

Dedicated Parts



Reconfigurable Parts



Spare Parts Requirements Model - II

Number of failures is limited by total parts due to no re-supply and repair:

$$0 \leq n_F \leq N$$

$$N = s_I + \sum_{e=1}^E q_e$$

For independent failures, the probability of no outstanding part order is:

$$A(t_i) = \frac{\#}{Q} - \frac{\bar{B}(t_i)}{Q}$$

Expected backorder level is function of available spares (and therefore of time):

$$\bar{B}_c(s, t_i) = \sum_{n_F = s+1}^N (n_F - s) p(n_F)$$

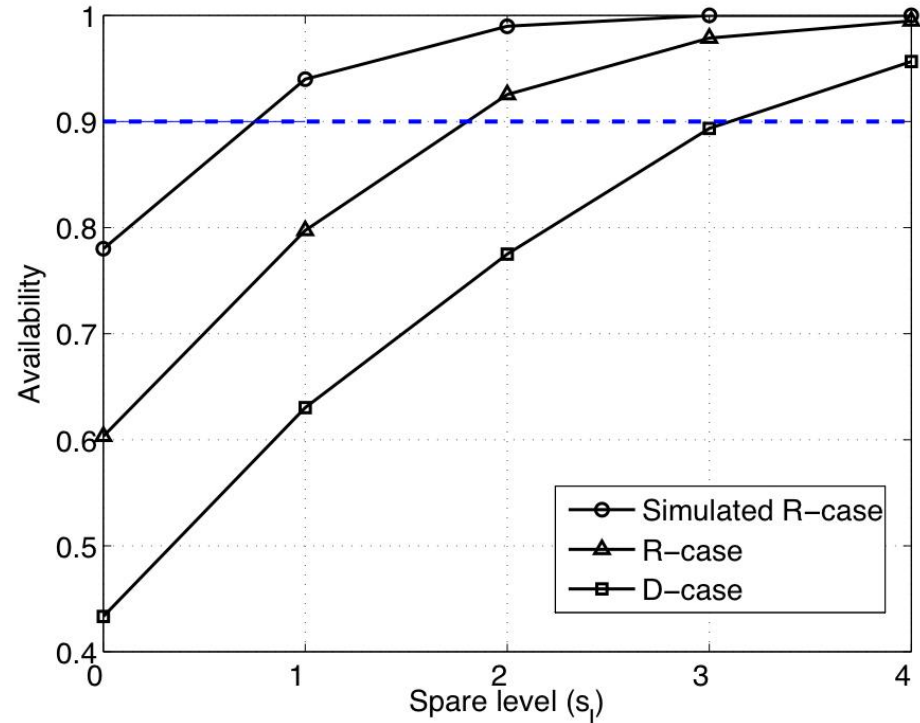
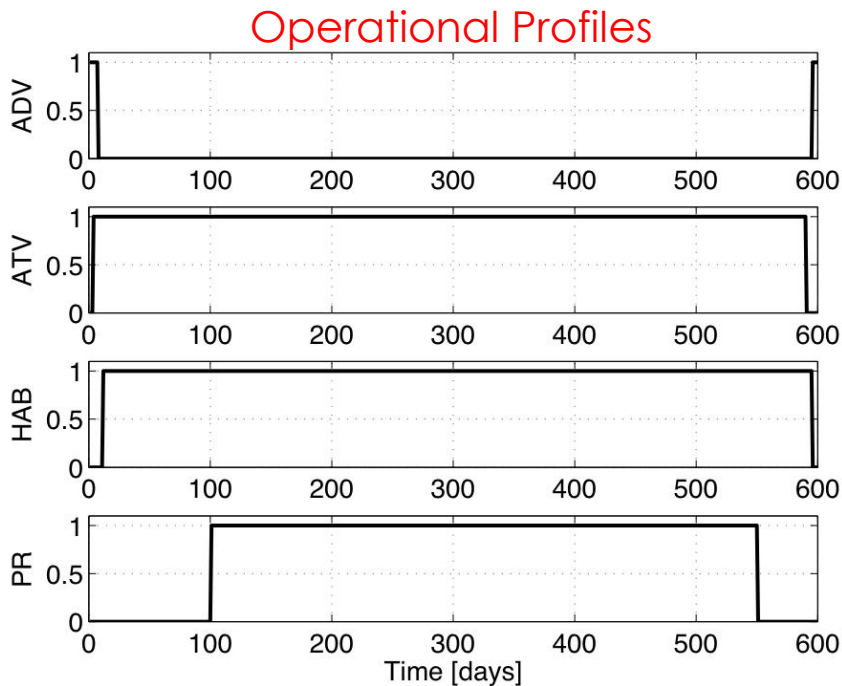
$$\bar{B}(t_i) = \sum_{s=0}^S \bar{B}_c(s, t_i) P(s)$$

$$A_{sys} = \min[A(t_i)] \quad t_i \in T$$

N: total number of parts
 $B_c(s, t)$: conditional backorder at spares level s
 P(s): probability of s spares being available
 $A(t_i)$: Availability at time t_i

Quantifying the Impact of Reconfigurability

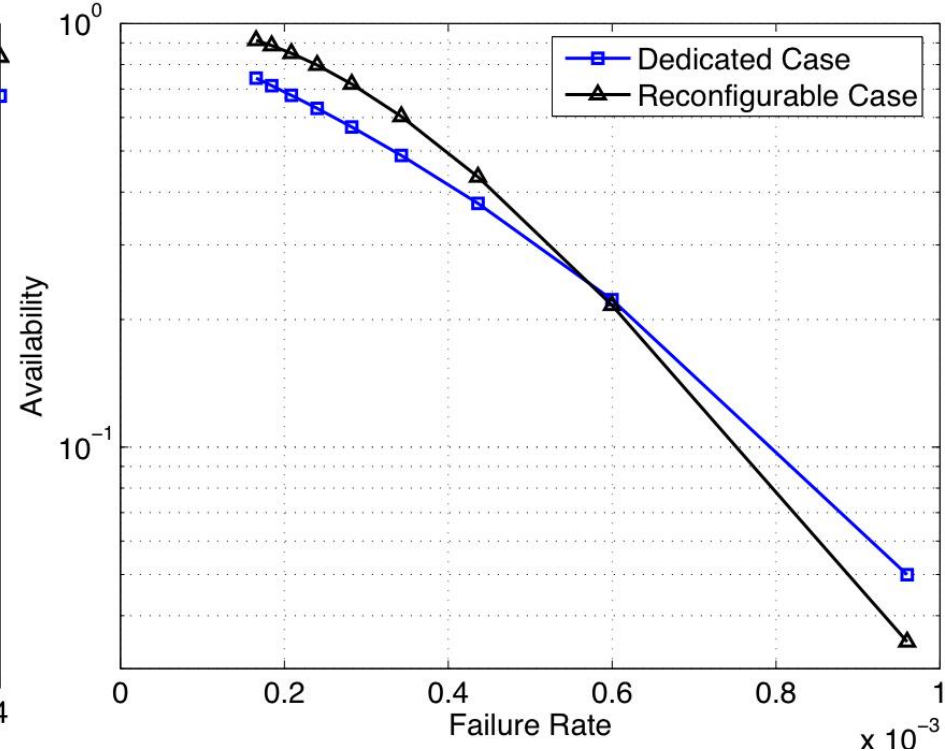
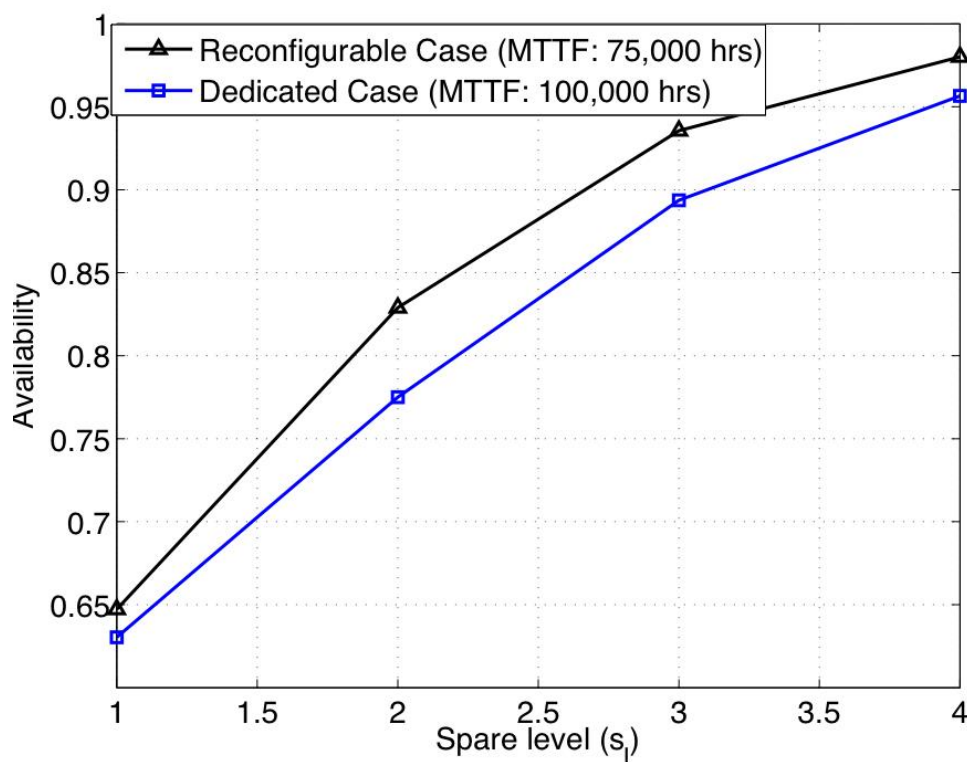
- Define co-located mission elements
- Define operational time profile, QPA *etc.*
- An Electronic Control Unit (ECU) with 100,000 hrs MTTF was used as an example



- Reconfigurable parts allow for 33-50% reduction in number of required spares for 90% Availability level

Benefits and Limitations

Increase in availability may be traded for reduced reliability (to affect component cost)

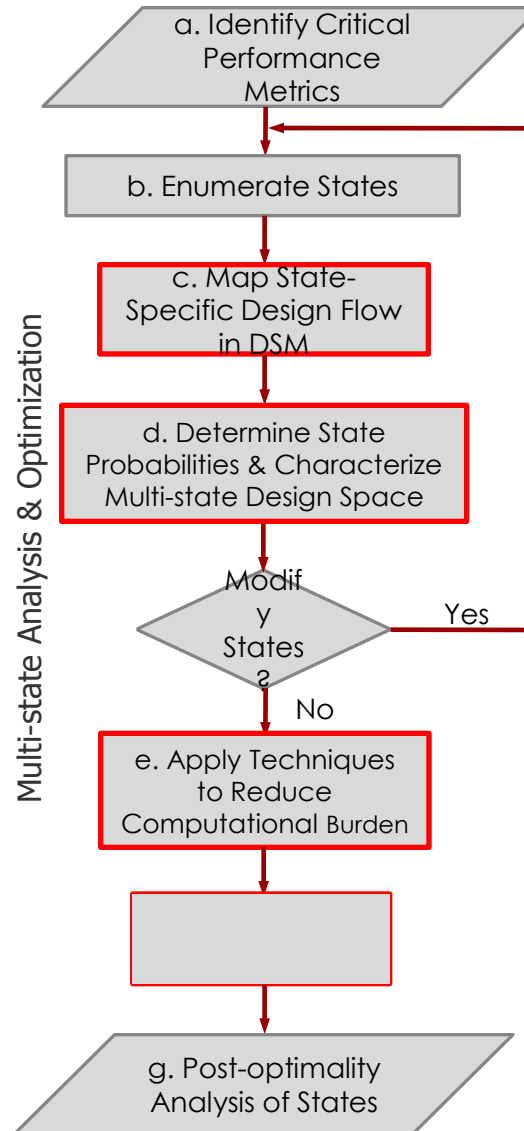


There is an eventual tradeoff between reconfigurable and dedicated parts if failure rates become high enough

Robustness of degraded aircraft (USAF)

- Aerospace systems spend significant time operating in **degraded or off-nominal states**
 - Yet current early-stage design focuses on improving performance in the nominal or most-likely state.
 - Future ultra long endurance vehicles require more attention to robustness in off-nominal states

Robustness – ability to perform under a variety of circumstances; ability to deliver desired functions in spite of changes in the environment, uses, or internal variations that are either built-in or emergent

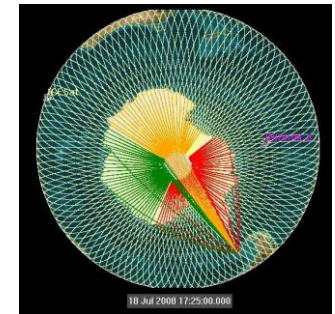


DARPA – Vulture

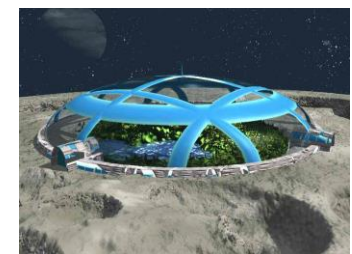


Vulture – stay aloft 5 years
No landing + repair allowed

NASA Antarctica UAV mission



5 years, 50kft, map ice sheets
Replace or complement IceSat



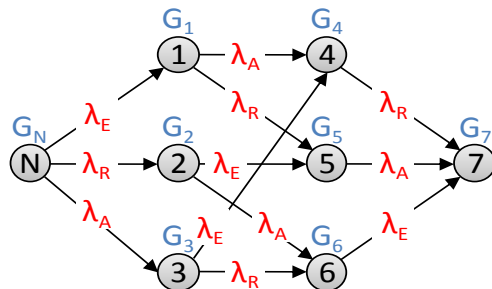
Space Colonization

PhD Thesis of J. Agte

King Air Twin Engine Case Study



C12-C Aircraft



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State	Left Engine	Rudder	Ailerons	Turn control
N				ailerons
1	failed			ailerons
2		failed		ailerons
3			failed	rudder
4	failed		failed	rudder
5	failed	failed		ailerons
6		failed	failed	diff. thrust
7	failed	failed	failed	none

Expected Availability

$$E_A = \sum_{m=1}^M A(W_M) \frac{T_M}{T} \quad \text{where} \quad A(W_M) = \sum_{G_k \geq W_M} p_k$$

$$E_G = \sum_{k=1}^K p_k G_k$$

Expected Performance

given parameters, c

$$\text{minimize } -E_G(\mathbf{x}, \mathbf{c}) = -\sum_{k=1}^K p_k G(\mathbf{x}, \mathbf{c})_k \quad \text{or} \quad -E_A(\mathbf{x}, \mathbf{c}) = -\sum_{m=1}^M A(W_M) \frac{T_M}{T}$$

$$\text{s.t. } h(\mathbf{x}, \mathbf{c}) = 0$$

$$g(\mathbf{x}, \mathbf{c}) = G_{N,req} / G_N(\mathbf{x}, \mathbf{c}) - 1 \leq 0$$

$$x_{i, LB} \leq x_i \leq x_{i, UB}$$

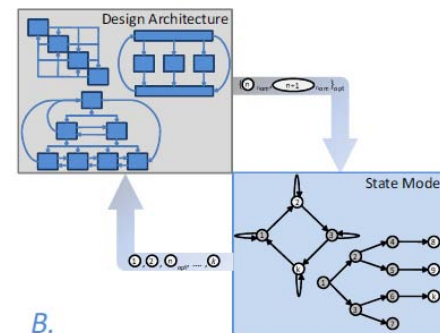
Agte J., Borer N., de Weck O., "Multistate Design Approach to the Analysis of Performance Robustness for a Twin-Engine Aircraft", *Journal of Aircraft*, 49(3), 781-793, May-June 2012

Aircraft Design Space

Design Variable:	Low Value	Baseline	High Value
Wing Area	272.7 ft ²	303 ft ²	333.3 ft ²
Wing Span	49.05 ft	54 ft	59.95 ft
Horizontal Tail Area	65.7 ft ²	73 ft ²	80.3 ft ²
Horizontal Tail Span	16.51 ft	18.3 ft	20.17 ft
Vertical Tail Area	105.12 ft ²	116.8 ft ²	128.48 ft ²
Vertical Tail Height	7.5 ft	8.33 ft	9.16 ft
Spanwise Engine Location	7.72 ft	8.58 ft	9.44 ft
Aileron Chord*	15.3%	23%	30.7%
Elevator Chord*	35.1%	41%	46.9%
Rudder Chord*	38.4%	44%	49.6%
Wing Sweep	0 deg	4 deg	15 deg

* Given in percent of wing, horizontal tail, or vertical tail chord.

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B.

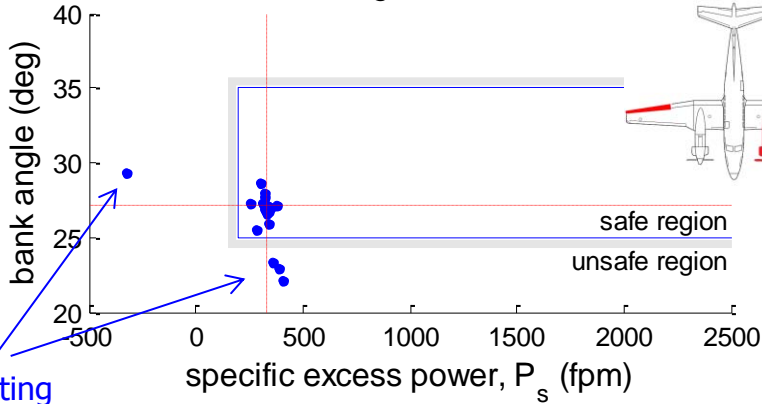


Actual (non-weighted) performance in each Markov state for the 23 geometry cases

Loss if $P_s < 200$ fpm, bank angle not held within 10 degrees

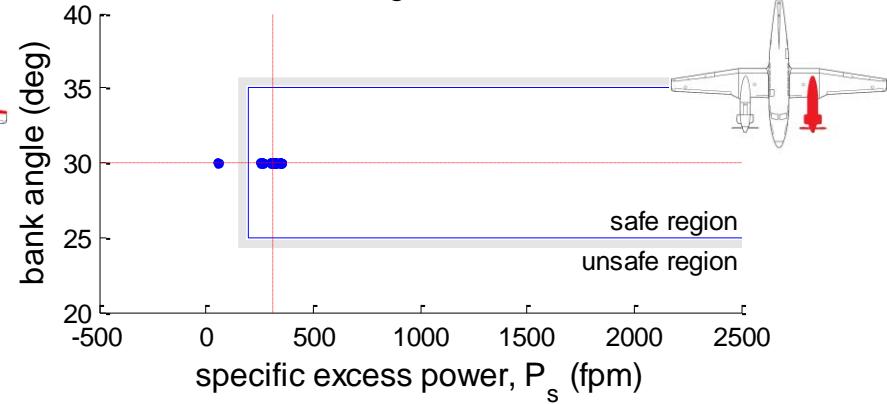
specific excess power, P_s (fpm)

State 4: Left Engine, Ailerons Failed



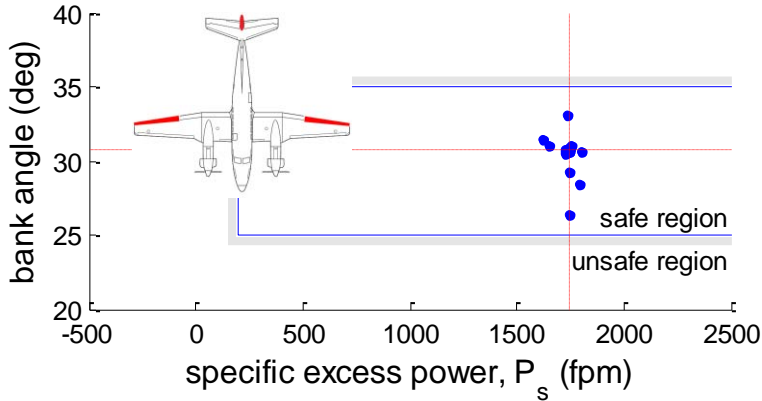
specific excess power, P_s (fpm)

State 5: Left Engine, Rudder Failed

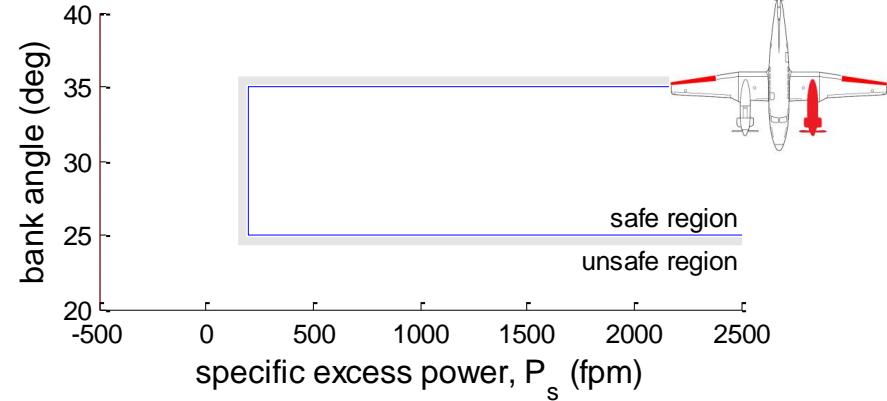


Interesting points

State 6: Rudder, Ailerons Failed



State 7: All Failed

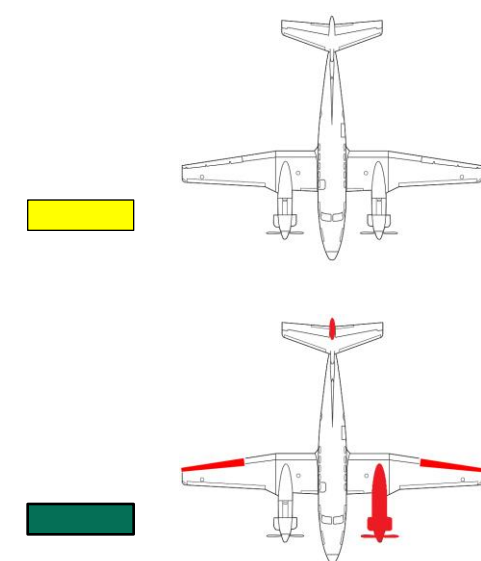
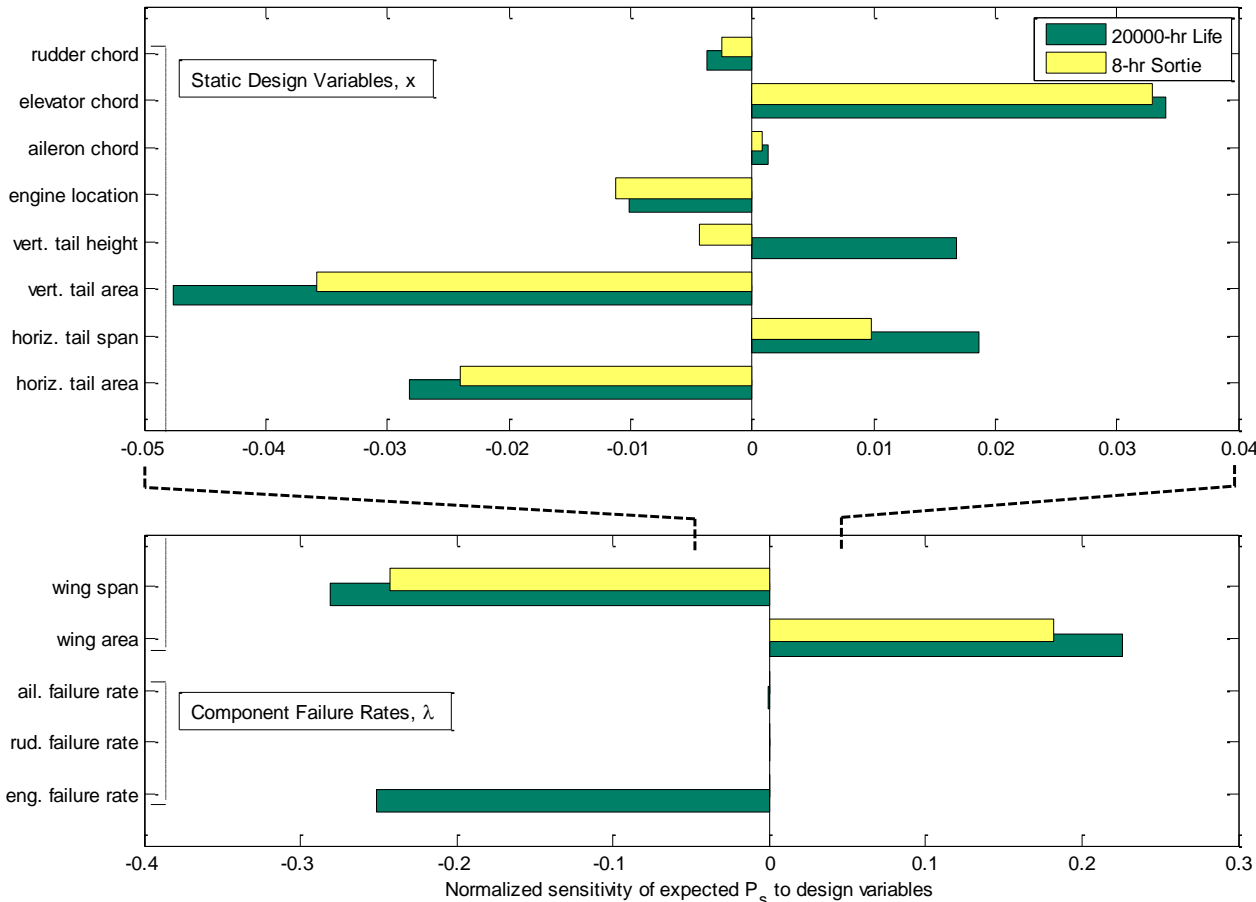


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Robustness requires off-nominal design optimization

Key result: aircraft geometry influences long-duration performance robustness more than component failure rates λ_i . Off-nominal control needed.

$$E_G(\mathbf{x}) = \sum_{k=1}^8 p_k(\mathbf{x}) P_s(\mathbf{x})_k = \sum_{k=1}^8 p_k(\mathbf{x}) \left[\dot{h}(\mathbf{x}) + \frac{V(\mathbf{x})}{g} \dot{V}(\mathbf{x}) \right]_{avg,k}$$



Design sensitivities when considering only nominal state (yellow) differ from those when considering expected performance across multiple states (green) → guidance towards robustness must include off-nominal states

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Post Flight Assessment Review (PFR)

- Also known as Post Launch Review (PLR)
 - Review telemetry from flight
 - Compare against predictions (e.g. from simulation)
 - Find / repair any failures
 - Secure data for later use
 - Initiate detailed commissioning / handover to operators

- A PFR-like review is part of the 2016 Cansat Competition

Table 6.7-18 PFAR Entrance and Success Criteria

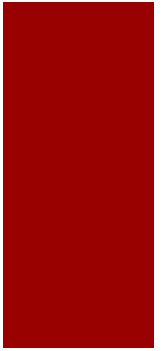
Post-Flight Assessment Review	
Entrance Criteria	Success Criteria
1. All anomalies that occurred during the mission, as well as during preflight testing, countdown, and ascent, identified.	1. Formal final report documenting flight performance and recommendations for future missions.
2. Report on overall post-recovery condition.	2. All anomalies have been adequately documented and disposed.
3. Report any evidence of ascent debris.	3. The impact of anomalies on future flight operations has been assessed.
4. All photo and video documentation available.	4. Plans for retaining assessment documentation and imaging have been made.
5. Retention plans for scrapped hardware completed.	5. Reports and other documentation have been added to a database for performance comparison and trending.
6. Post-flight assessment team operating plan completed.	
7. Disassembly activities planned and scheduled.	
8. Processes and controls to coordinate in-flight anomaly troubleshooting and post-flight data preservation developed.	
9. Problem reports, corrective action requests, post-flight anomaly records, and final post-flight documentation completed.	
10. All post-flight hardware and flight data evaluation reports completed.	

Summary: Ops Checklist

- System checkout in lab/hangar/field; everything working OK?
- Bring sufficient consumables (batteries, fuel, lubricants etc...), including reserves
- Spare parts and tools to repair
- Other support equipment (remote control, telemetry, cameras ...)
- Training operators and support personnel
- Checklist for normal operations and emergency/contingencies
- Transportation logistics (forward and reverse)
- Plan in enough time for commissioning → before operations

Reminders for PDR (next week)

- Check Schedule – be on time
- Upload slide deck beforehand
- 30 min PDR presentation
- Followed by up to 30 min Q&A



Questions?

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