

14.462 Lecture Notes

Commitment, Coordination, and Expectation Traps

George-Marios Angeletos
MIT Department of Economics
Spring 2004

1 Kydland Prescott/Barro Gordon

A large number of private agents play against a government.

The government solves

$$\min L = \{(y - y^*)^2 + \beta\pi^2\}$$

subject to the Philips curve

$$y = \bar{y} + \alpha(\pi - \pi_e) - \varepsilon.$$

The shock ε is distributed uniform over $[-e, +e]$

The agents solve

$$\min \mathbb{E} (\pi_e - \pi)^2$$

The agents move first, setting π^e without observing ε . Nature then draws ε . The government moves last, setting π after observing ε and taking π^e as given.

The best response of the government is given by

$$\pi = g(\pi_e, \varepsilon) = \frac{\alpha(y^* - \bar{y} + \varepsilon) + \alpha^2\pi_e}{\alpha^2 + \beta}.$$

Note that $g(0, 0) > 0$ and $g_\pi(\pi, \varepsilon) = \frac{\alpha^2}{\alpha^2 + \beta} \in (0, 1)$. The best response for the agents is

$$\pi_e = \mathbb{E}\pi$$

Hence, in equilibrium,

$$\pi_e = \mathbb{E}g(\pi_e, \varepsilon) = \frac{\alpha(y^* - \bar{y}) + \alpha^2\pi_e}{\alpha^2 + \beta} \equiv G(\pi_e).$$

By the properties of g , we have $G(0)$ and $G' \in (0, 1)$. Hence, there is a unique fixed point with $\pi_e > 0$. Indeed, this is given by

$$\pi_e = \frac{\alpha(y^* - \bar{y})}{\beta}.$$

It follows that equilibrium inflation is

$$\pi = \pi_e + \frac{\alpha}{\alpha^2 + \beta}\varepsilon$$

and equilibrium output is

$$y = \bar{y} + \frac{\alpha^2}{\alpha^2 + \beta}\varepsilon.$$

2 Obstfeld (1994)

We now reinterpret π as the rate of devaluation. We also modify the preferences of the government so that the government solves

$$\min L = \{(y - y^*)^2 + \beta\pi^2 + \theta R\}$$

subject to the Philips curve, where R is an indicator that takes the value 1 if $\pi \neq 0$ and 0 if $\pi = 0$. The variable θ represents the value of maintaining the peg.

The timing is the same. The government chooses π after observing ε and after agents have set π_e .

If the government sets $\pi = g(\pi_e, \varepsilon)$, then welfare losses are given by

$$L = L_{flex}(\pi_e, \varepsilon) = \frac{\beta}{\alpha^2 + \beta} (y^* - \bar{y} + \varepsilon + \alpha\pi^e)^2 + \theta.$$

If instead the government sets $\pi = 0$, then welfare losses are given by

$$L = L_{fixed}(\pi_e, \varepsilon) = (y^* - \bar{y} + \varepsilon + \alpha\pi^e)^2$$

Define $\underline{\varepsilon} = \underline{\varepsilon}(\pi_e)$ and $\bar{\varepsilon} = \bar{\varepsilon}(\pi_e)$ as the lowest and highest solution to

$$L_{flex}(\pi_e, \varepsilon) = L_{fixed}(\pi_e, \varepsilon).$$

Whenever $\varepsilon \in [\underline{\varepsilon}, \bar{\varepsilon}]$, the government finds it optimal to set $\pi = 0$ (fixed). Whenever $\varepsilon \notin [\underline{\varepsilon}, \bar{\varepsilon}]$, the government prefers to set $\pi = g(\pi_e)$ (flexibility).

Now consider the equilibrium. In equilibrium,

$$\pi^e = \mathbb{E}\pi = 0 \cdot \Pr(\varepsilon \in [\underline{\varepsilon}, \bar{\varepsilon}]) + \mathbb{E}g(\pi_e, \varepsilon) \cdot \Pr(\varepsilon \notin [\underline{\varepsilon}, \bar{\varepsilon}]) \equiv G(\pi_e)$$

Note that as π_e increases, the interval $[\underline{\varepsilon}, \bar{\varepsilon}]$ shifts down. It can be shown that $G(0) > 0$, $G' > 0$ and, over some range, $G' > 1$. Hence, G may possibly have either a unique or multiple fixed points, depending on the value of θ .

The graph of G is illustrated in Figure 1. For θ either small enough or large enough, the unique equilibrium is unique. But for intermediate value of θ , there are multiple equilibria. In particular, for intermediate θ , there are three equilibria, represented by points A , B , and C in the figure. In point C , the peg is always abandoned. In point A , the peg is abandoned only for very extreme shocks. The equilibrium in C thus represents an “expectations trap”. On the other hand, only the “bad” equilibrium (C) survives for θ small enough, whereas only the “good” equilibrium (A') survives for θ high enough.

Discuss the role of coordination and the role of commitment.

Discuss Albanesi, Chari and Christiano (2000).

Discuss Fisher (19??).

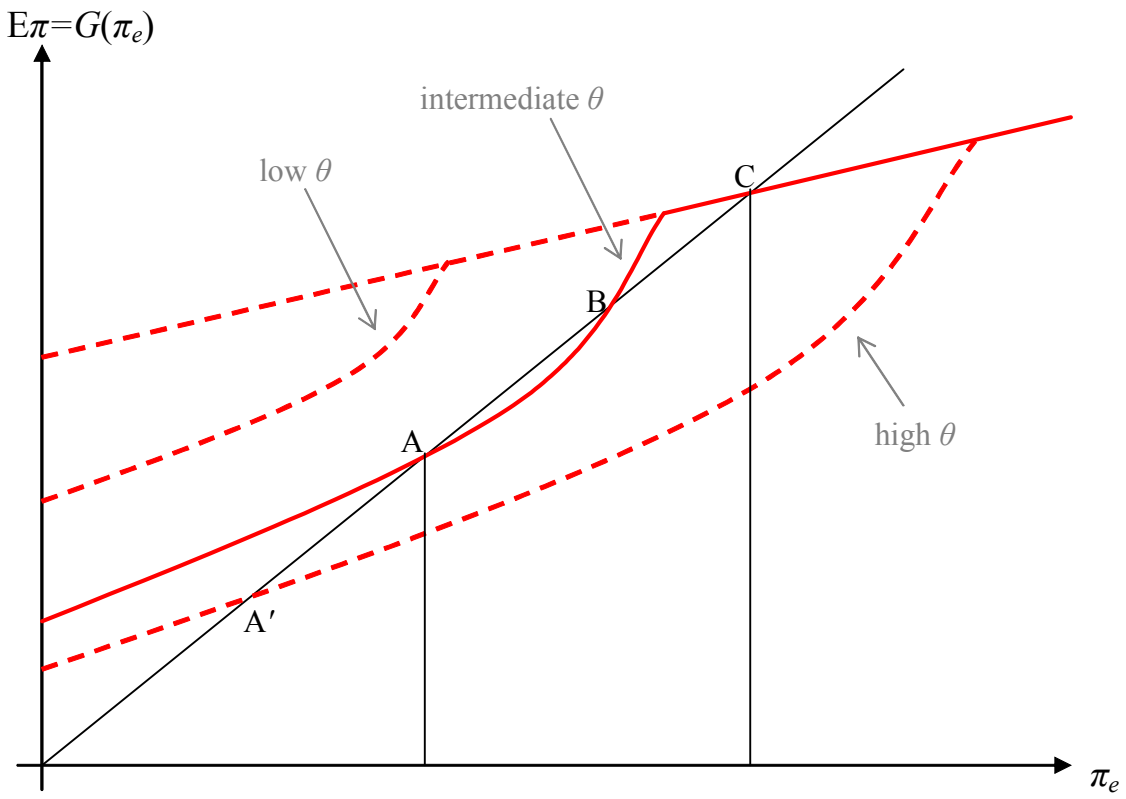


Figure 1: