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6.006 Introduction to Algorithms  
Spring 2008

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# 6.006 Recitation

Build 2008.23

# 6.006 Proudly Presents

- Two-Way BFS
- Stable Sorting
- DRY

# Two-Way BFS

Regular BFS

Two-Way BFS

Start: from source

Start: from both the source  
and the goal

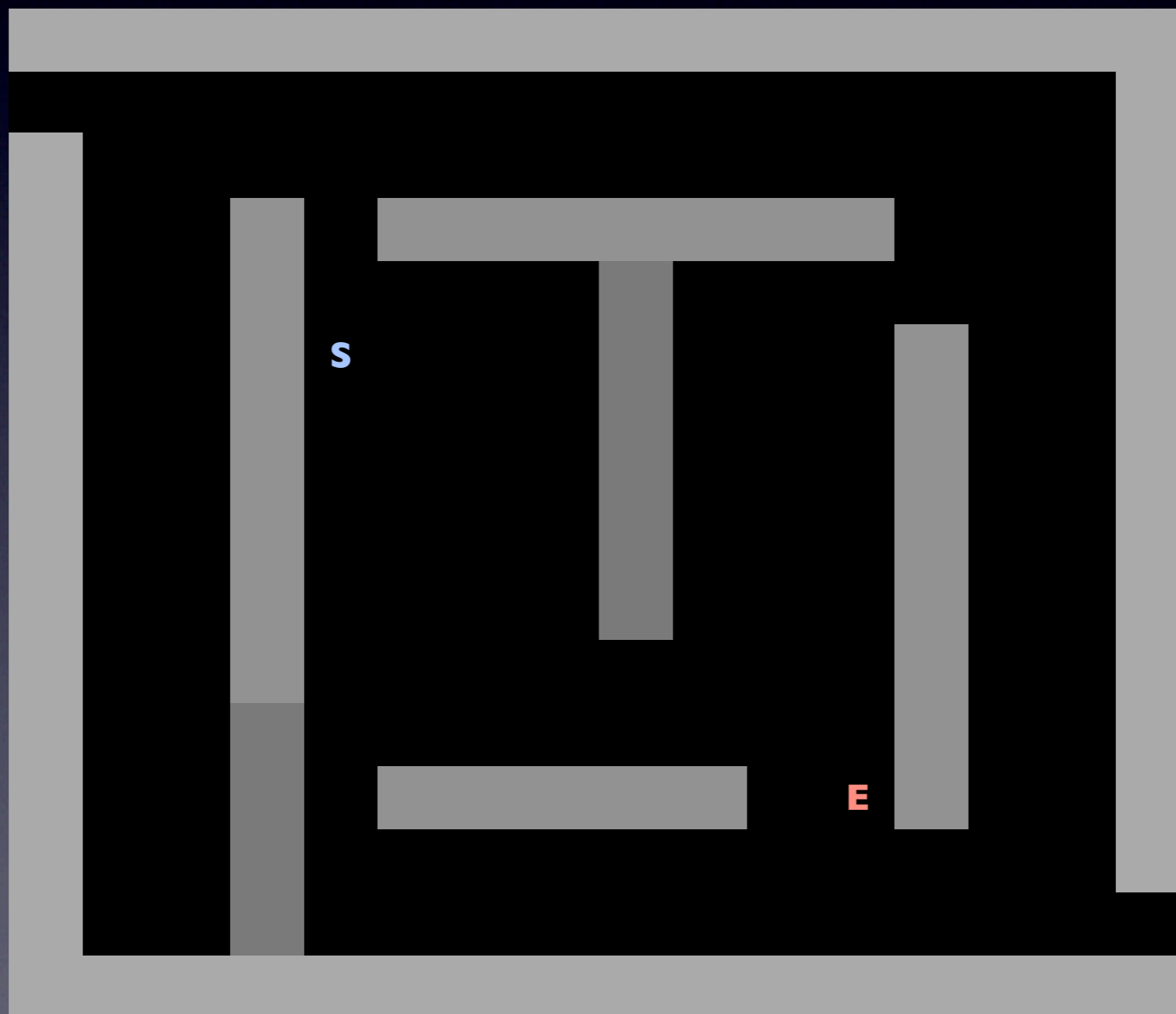
End: reached a goal

End: a node is reached both  
from source and from goal

Works with multiple goals

Requires single goal

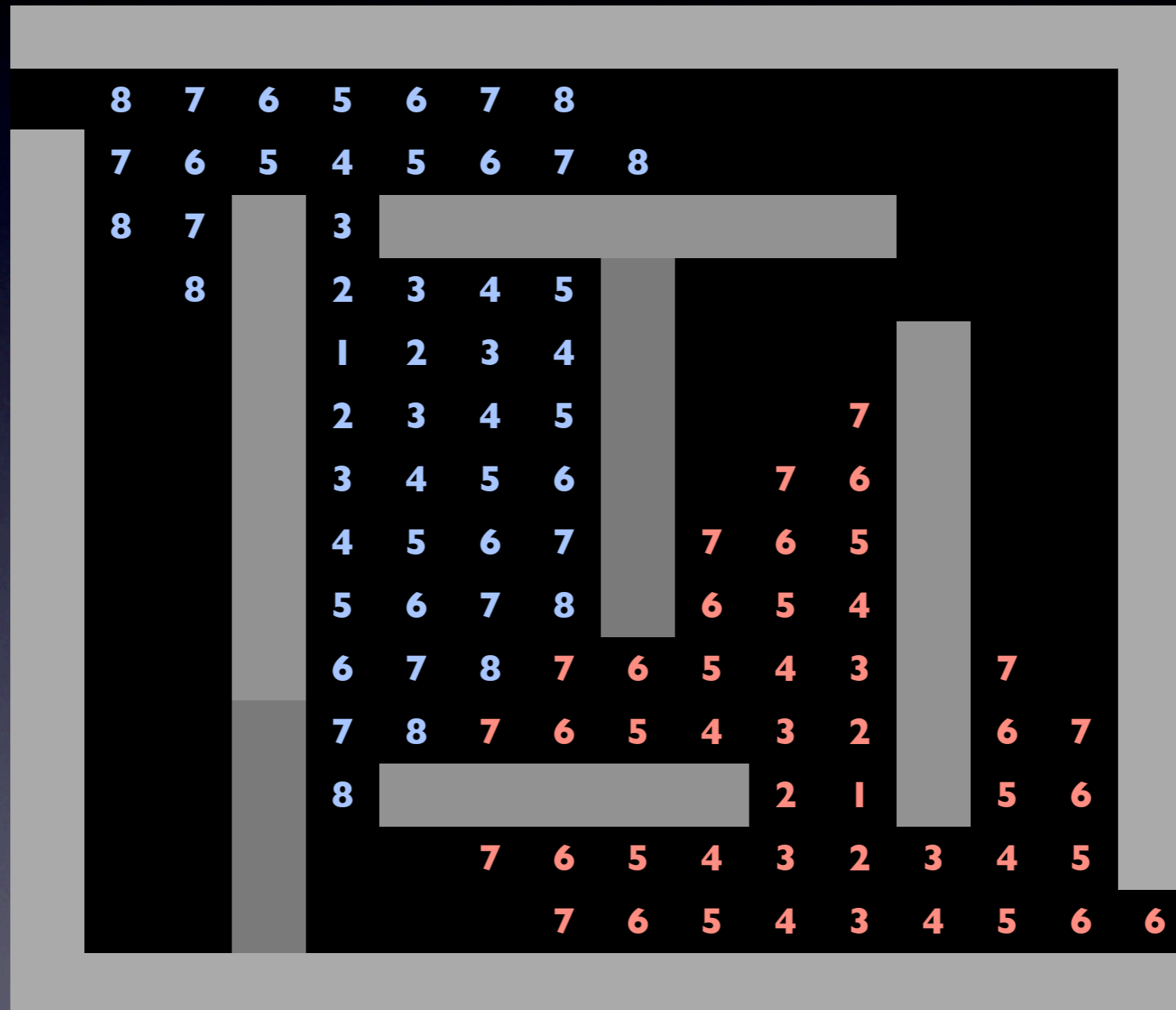
# Poking Aftermath: (gasp) Meeting Her



# BFS

8	7	6	5	6	7	8	9	10	11	12	13	14	15
7	6	5	4	5	6	7	8	9	10	11	12	13	14
8	7		3								13	14	15
9	8		2	3	4	5				15	14	15	
10	9		1	2	3	4							
11	10		2	3	4	5		15					
12	11		3	4	5	6		14	15				
13	12		4	5	6	7		13	14	15			
14	13		5	6	7	8		12	13	14			
15	14		6	7	8	9	10	11	12	13			
	15		7	8	9	10	11	12	13	14			
			8							14	E		
			9	10	11	12	13	14	15				
			10	11	12	13	14	15					

# Two-Way BFS



# Two-Way BFS

## Implementation Talk

```
1 def bfs(g, s):
2     r = BFSResults()
3     actives = deque()
4     actives.append(s)
5     r.parent[s] = None
6     r.level[s] = 0
7
8     while len(actives):
9         v = actives.popleft()
10        for n in g.neighbors(v):
11            if n not in r.parent:
12                r.parent[n] = v
13                r.level[n] = r.level[v] + 1
14                actives.append(n)
15    return r
```



# Stable Sorting

- Property of sorting algorithms
  - It's not Yet Another Sorting Algorithm
- Maintains the relative order of equal keys
- Desirable in some grand scheme of things (like Radix Sort)

# Stable Sorting: Example

3    1    4'    1'    5    2    7    4    6    4''

1    1'    2    3    4'    4    4''    5    6    7

1'    1    2    3    4    4'    4''    5    6    7

# Don't Repeat Yourself (DRY)

- Code one decision in one place
  - No magic constants all over the code
  - Easy to change your mind (once you found the code for that decision, you don't have to dig deeper)
- Useful every day, priceless in large systems
- Do use: functions, constants, local variables

```

1 def detect_collisions(balls):
2     set_of_collisions = set()
3     x_cells = int((gas.world_max_x - gas.world_min_x) / 256) + 1
4     y_cells = int((gas.world_max_y - gas.world_min_y) / 256) + 1
5     grid = [[[] for i in range(x_cells)] for i in range(y_cells)]
6     for b in balls:
7         grid[int((b.x - gas.world_min_x) / 256)][int((b.y - gas.world_min_y) /
256)].append(b)
8
9     for xc in range(x_cells):
10        for yc in range(y_cells):
11            for xp in [-1, 0, 1]:
12                for yp in [-1, 0, 1]:
13                    if xc + xp < 0 or xc + xp >= x_cells:
14                        continue
15                    if yc + yp < 0 or yc + yp >= y_cells:
16                        continue
17                    for b1 in grid[xc][yc]:
18                        for b2 in grid[xc + xp][yc + yp]:
19                            if b1.id < b2.id and gas.colliding(b1, b2):
20                                set_of_collisions.add(gas.ball_pair(b1, b2))
21        return set_of_collisions
22
23 import gas
24 gas.detect_collisions = detect_collisions
25 if __name__ == "__main__":
26     gas.main()

```

# Questions

Better have some!