

# **Lecture 16**

## **The QR Algorithm II**

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Introduction to Numerical Methods

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# Simultaneous *Inverse* Iteration $\iff$ QR Algorithm

- Last lecture we showed that “pure” QR  $\iff$  simultaneous iteration applied to  $I$ , and the first column evolves as in power iteration
- But it is also equivalent to simultaneous *inverse* iteration applied to a “flipped”  $I$ , and the last column evolves as in inverse iteration
- To see this, recall that  $A^k = \underline{Q}^{(k)} \underline{R}^{(k)}$  with

$$\underline{Q}^{(k)} = \prod_{j=1}^k Q^{(j)} = \left[ \begin{array}{c|c|c|c} q_1^{(k)} & q_2^{(k)} & \cdots & q_m^{(k)} \end{array} \right]$$

- Invert and use that  $A^{-1}$  is symmetric:

$$A^{-k} = (\underline{R}^{(k)})^{-1} \underline{Q}^{(k)T} = \underline{Q}^{(k)} (\underline{R}^{(k)})^{-T}$$

# Simultaneous *Inverse Iteration* $\iff$ QR Algorithm

- Introduce the “flipping” permutation matrix

$$P = \begin{bmatrix} & & & 1 \\ & & & \\ & & 1 & \\ \dots & & & \\ 1 & & & \end{bmatrix}$$

and rewrite that last expression as

$$A^{-k} P = [\underline{Q}^{(k)} P][P(\underline{R}^{(k)})^{-T} P]$$

- This is a QR factorization of  $A^{-k} P$ , and the algorithm is equivalent to simultaneous iteration on  $A^{-1}$
- In particular, the last column of  $\underline{Q}^{(k)}$  evolves as in inverse iteration

# The Shifted QR Algorithm

- Since the QR algorithm behaves like inverse iteration, introduce shifts  $\mu^{(k)}$  to accelerate the convergence:

$$A^{(k-1)} - \mu^{(k)} I = Q^{(k)} R^{(k)}$$

$$A^{(k)} = R^{(k)} Q^{(k)} + \mu^{(k)} I$$

- We then get (same as before):

$$A^{(k)} = (Q^{(k)})^T A^{(k-1)} Q^{(k)} = (\underline{Q}^{(k)})^T A \underline{Q}^{(k)}$$

and (different from before):

$$(A - \mu^{(k)} I)(A - \mu^{(k-1)} I) \cdots (A - \mu^{(1)} I) = \underline{Q}^{(k)} \underline{R}^{(k)}$$

- Shifted simultaneous iteration – last column of  $\underline{Q}^{(k)}$  converges quickly

# Choosing $\mu^{(k)}$ : The Rayleigh Quotient Shift

- Natural choice of  $\mu^{(k)}$ : Rayleigh quotient for last column of  $\underline{Q}^{(k)}$

$$\mu^{(k)} = \frac{(q_m^{(k)})^T A q_m^{(k)}}{(q_m^{(k)})^T q_m^{(k)}} = (q_m^{(k)})^T A q_m^{(k)}$$

- Rayleigh quotient iteration, last column  $q_m^{(k)}$  converges cubically
- Convenient fact: This Rayleigh quotient appears as  $m, m$  entry of  $A^{(k)}$  since  $A^{(k)} = (\underline{Q}^{(k)})^T A \underline{Q}^{(k)}$
- The *Rayleigh quotient shift* corresponds to setting  $\mu^{(k)} = A_{mm}^{(k)}$

# Choosing $\mu^{(k)}$ : The Wilkinson Shift

- The QR algorithm with Rayleigh quotient shift might fail, e.g. with two symmetric eigenvalues
- Break symmetry by the *Wilkinson shift*

$$\mu = a_m - \text{sign}(\delta)b_{m-1}^2 / \left( |\delta| + \sqrt{\delta^2 + b_{m-1}^2} \right)$$

where  $\delta = (a_{m-1} - a_m)/2$  and  $B = \begin{bmatrix} a_{m-1} & b_{m-1} \\ b_{m-1} & a_m \end{bmatrix}$  is the lower-right submatrix of  $A^{(k)}$

- Always convergence with this shift, in worst case quadratically

# A Practical Shifted QR Algorithm

## Algorithm: “Practical” QR Algorithm

$$(Q^{(0)})^T A^{(0)} Q^{(0)} = A$$

$A^{(0)}$  is a tridiagonalization of  $A$

**for**  $k = 1, 2, \dots$

Pick a shift  $\mu^{(k)}$

e.g., choose  $\mu^{(k)} = A_{mm}^{(k-1)}$

$$Q^{(k)} R^{(k)} = A^{(k-1)} - \mu^{(k)} I$$

QR factorization of  $A^{(k-1)} - \mu^{(k)} I$

$$A^{(k)} = R^{(k)} Q^{(k)} + \mu^{(k)} I$$

Recombine factors in reverse order

If any off-diagonal element  $A_{j,j+1}^{(k)}$  is sufficiently close to zero,

set  $A_{j,j+1} = A_{j+1,j} = 0$  to obtain

$$\begin{bmatrix} A_1 & 0 \\ 0 & A_2 \end{bmatrix} = A^{(k)}$$

and now apply the QR algorithm to  $A_1$  and  $A_2$

# Stability and Accuracy

- The QR algorithm is backward stable:

$$\tilde{Q}\tilde{\Lambda}\tilde{Q}^T = A + \delta A, \quad \frac{\|\delta A\|}{\|A\|} = O(\epsilon_{\text{machine}})$$

where  $\tilde{\Lambda}$  is the computed  $\Lambda$  and  $\tilde{Q}$  is an exactly orthogonal matrix

- The combination with Hessenberg reduction is also backward stable
- Can be shown (for normal matrices) that  $|\tilde{\lambda}_j - \lambda_j| \leq \|\delta A\|_2$ , which gives

$$\frac{|\tilde{\lambda}_j - \lambda_j|}{\|A\|} = O(\epsilon_{\text{machine}})$$

where  $\tilde{\lambda}_j$  are the computed eigenvalues

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