

## Formula Sheet Exam 2

Springs and masses:

$$m \frac{d^2}{dt^2} x(t) + b \frac{d}{dt} x(t) + kx(t) = F(t)$$

More general differential equation with harmonic driving force:

$$\frac{d^2}{dt^2} x(t) + \Gamma \frac{d}{dt} x(t) + \omega_0^2 x(t) = \frac{F_0}{m} \cos(\omega_d t)$$

Steady state solutions:

$$x_s(t) = A \cos(\omega_d t - \delta)$$

where

$$A = \frac{\frac{F_0}{m}}{\sqrt{(\omega_0^2 - \omega_d^2)^2 + \omega_d^2 \Gamma^2}}$$

and

$$\tan \delta = \frac{\Gamma \omega_d}{\omega_0^2 - \omega_d^2}$$

General solutions:

For  $\Gamma = 0$  (undamped system):

$$x(t) = R \cos(\omega_0 t + \theta) + x_s(t)$$

where  $R$  and  $\theta$  are unknown coefficients.

For  $\Gamma < 2\omega_0$  (under damped system):

$$x(t) = R e^{-\frac{\Gamma}{2}t} \cos\left(\sqrt{\omega_0^2 - \frac{\Gamma^2}{4}} t + \theta\right) + x_s(t)$$

where  $R$  and  $\theta$  are unknown coefficients.

For  $\Gamma = 2\omega_0$  (critically damped system):

$$x(t) = (R_1 + R_2 t) e^{-\frac{\Gamma}{2}t} + x_s(t)$$

where  $R_1$  and  $R_2$  are unknown coefficients.

For  $\Gamma > 2\omega_0$  (over damped system):

$$x(t) = R_1 e^{-\left(\frac{\Gamma}{2} + \sqrt{\frac{\Gamma^2}{4} - \omega_0^2}\right)t} + R_2 e^{-\left(\frac{\Gamma}{2} - \sqrt{\frac{\Gamma^2}{4} - \omega_0^2}\right)t} + x_s(t)$$

where  $R_1$  and  $R_2$  are unknown coefficients.

Coupled oscillators

$$F_j = - \sum_{k=1}^n K_{jk} x_k$$

Examples for  $n = 2$

$$\mathcal{X}(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$$

$$\mathcal{K} = \begin{bmatrix} K_{11} & K_{12} \\ K_{21} & K_{22} \end{bmatrix}$$

$$\mathcal{M} = \begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix}$$

Matrix equation of motion, matrices  $\mathcal{M}$ ,  $\mathcal{K}$ ,  $\mathcal{I}$  are  $n \times n$ , vectors  $\mathcal{X}$ ,  $\mathcal{Z}$  are  $n \times 1$ .

$$\frac{d^2}{dt^2} \mathcal{X}(t) = -\mathcal{M}^{-1} \mathcal{K} \mathcal{X}(t)$$

$$\mathcal{Z}(t) = \mathcal{A} e^{-i\omega t}$$

$$(\mathcal{M}^{-1} \mathcal{K} - \omega^2 \mathcal{I}) \mathcal{A} = 0$$

To obtain the frequencies of normal modes solve:

$$\det(\mathcal{M}^{-1} \mathcal{K} - \omega^2 \mathcal{I}) = 0$$

For  $n = 2$

$$\det \begin{bmatrix} M_{11} & M_{12} \\ M_{21} & M_{22} \end{bmatrix} = M_{11} M_{22} - M_{12} M_{21}$$

If the system is driven by force one can find the response amplitudes  $\mathcal{C}(\omega_d)$

$$\mathcal{F}(t) = \mathcal{F}_0 e^{-i\omega_d t}$$

$$\mathcal{W}(t) = \mathcal{C}(\omega_d) e^{-i\omega_d t}$$

$$\mathcal{C}(\omega_d) = \begin{bmatrix} c_1(\omega_d) \\ c_2(\omega_d) \end{bmatrix}$$

$$(\mathcal{M}^{-1} \mathcal{K} - \omega_d^2 \mathcal{I}) \mathcal{C}(\omega_d) = \mathcal{F}_0$$

solving the equation above one can find the response amplitudes for the first ( $c_1(\omega_d)$ ) and second ( $c_2(\omega_d)$ ) objects in the system.

Reflection symmetry matrix:

$$\mathcal{S} = \begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$$

Eigenvalues ( $\beta$ ) and eigenvectors ( $\mathcal{A}$ ) of this  $2 \times 2$   $\mathcal{S}$  matrix:

$$(1) \beta = -1, \mathcal{A} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$(2) \beta = 1, \mathcal{A} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

1D infinite coupled system which satisfy space translation symmetry:

Given a eigenvalue  $\beta$ , the corresponding eigenvector is

$$A_j = \beta^j A_0$$

where

$$A_j(A_0)$$

is the normal amplitude of  $j$ th(0th) object in the system.

Consider an one dimensional system which consists infinite number of masses coupled by springs,  $\beta$  can be written as  $\beta = e^{ika}$  where  $k$  is the wave number and  $a$  is the distance between the masses.

Kirchoff's Laws (be careful about the signs!)

$$\text{Node : } \sum_i I_i = 0 \quad \text{Loop : } \sum_i \Delta V_i = 0$$

$$\text{Capacitors : } \Delta V = \frac{Q}{C} \quad \text{Inductors : } \Delta V = -L \frac{dI}{dt} \quad \text{Current : } I = \frac{dQ}{dt}$$

Trigonometric equalities:

$$\sin(a \pm b) = \sin(a) \cos(b) \pm \cos(a) \sin(b)$$

$$\cos(a \pm b) = \cos(a) \cos(b) \mp \sin(a) \sin(b)$$

$$\sin(a) + \sin(b) = 2 \sin\left(\frac{a+b}{2}\right) \cos\left(\frac{a-b}{2}\right)$$

$$\sin(a) - \sin(b) = 2 \cos\left(\frac{a+b}{2}\right) \sin\left(\frac{a-b}{2}\right)$$

$$\cos(a) + \cos(b) = 2 \cos\left(\frac{a+b}{2}\right) \cos\left(\frac{a-b}{2}\right)$$

$$\cos(a) - \cos(b) = -2 \sin\left(\frac{a+b}{2}\right) \sin\left(\frac{a-b}{2}\right)$$

Integrals involving sin and cos:

$$\frac{2}{L} \int_0^L \sin\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx = \begin{cases} 1, & \text{if } n = m. \\ 0, & \text{otherwise.} \end{cases}$$

$$\frac{2}{L} \int_0^L \cos\left(\frac{n\pi x}{L}\right) \cos\left(\frac{m\pi x}{L}\right) dx = \begin{cases} 1, & \text{if } n = m. \\ 0, & \text{otherwise.} \end{cases}$$

$$\frac{2}{L} \int_0^L \cos\left(\frac{n\pi x}{L}\right) \sin\left(\frac{m\pi x}{L}\right) dx = 0$$

$$\int x \sin(x) dx = \sin(x) - x \cos(x) + C$$

$$\int x \cos(x) dx = \cos(x) + x \sin(x) + C$$

Maxwell Equations in vacuum

$$\begin{aligned} \frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} &= -\frac{\partial B_z}{\partial t}; & \frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} &= -\frac{\partial B_x}{\partial t}; & \frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} &= -\frac{\partial B_y}{\partial t} \\ \frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} &= \mu_0 \epsilon_0 \frac{\partial E_z}{\partial t}; & \frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} &= \mu_0 \epsilon_0 \frac{\partial E_x}{\partial t}; & \frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} &= \mu_0 \epsilon_0 \frac{\partial E_y}{\partial t} \\ \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} &= 0; & \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} &= 0 \end{aligned}$$

Wave equation for EM fields in vacuum

$$\begin{aligned} \frac{\partial^2 E_i}{\partial x^2} + \frac{\partial^2 E_i}{\partial y^2} + \frac{\partial^2 E_i}{\partial z^2} &= \frac{1}{c^2} \frac{\partial^2 E_i}{\partial t^2} \text{ where } i = x, y, z \\ \frac{\partial^2 B_i}{\partial x^2} + \frac{\partial^2 B_i}{\partial y^2} + \frac{\partial^2 B_i}{\partial z^2} &= \frac{1}{c^2} \frac{\partial^2 B_i}{\partial t^2} \text{ where } i = x, y, z \end{aligned}$$

For EM plane waves in vacuum:

$$\begin{aligned} \vec{B}(\vec{r}, t) &= \frac{1}{c} \hat{k} \times \vec{E}(\vec{r}, t) \\ \vec{E}(\vec{r}, t) &= c \vec{B}(\vec{r}, t) \times \hat{k} \end{aligned}$$

Linear energy density in a string with tension  $T$  and mass density  $\rho_L$

$$\frac{dK}{dx} = \frac{1}{2} \rho_L \left( \frac{\partial y}{\partial t} \right)^2 \quad \frac{dU}{dx} = \frac{1}{2} T \left( \frac{\partial y}{\partial x} \right)^2$$

EM energy per unit volume and Poynting vector:

$$U_E = \frac{1}{2} \epsilon_0 \vec{E}^2 \quad U_B = \frac{1}{2\mu_0} \vec{B}^2 \quad \vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$

Transmission and reflection

$$R = \frac{z_1 - z_2}{z_2 + z_1} \quad T = \frac{2z_1}{z_2 + z_1}$$

Phase velocity and impedance:

$$\begin{aligned} v &= \sqrt{\frac{T}{\rho_L}} & Z &= \sqrt{T \rho_L} \text{ (string)} \\ v &= \sqrt{\frac{1}{LC}} & Z &= \sqrt{\frac{L}{C}} \text{ (transmission line)} \end{aligned}$$

Snell's law

$$n_1 \sin \theta_1 = n_2 \sin \theta_2$$

Fourier transform

$$f(t) = \int_{-\infty}^{\infty} d\omega C(\omega) e^{-i\omega t}$$
$$C(\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} dt f(t) e^{i\omega t}$$

Delta function

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} e^{i(\omega - \omega')t} dt = \delta(\omega - \omega')$$
$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$
$$\int_{-\infty}^{\infty} \delta(x - a) f(x) dx = f(a)$$

MIT OpenCourseWare  
<https://ocw.mit.edu>

8.03SC Physics III: Vibrations and Waves  
Fall 2016

For information about citing these materials or our Terms of Use, visit: <https://ocw.mit.edu/terms>.